

## Drawing up a road plan in difficult sections

A. Artykbaev<sup>1</sup>, M.M. Toshmatova<sup>1</sup>

<sup>1</sup>Tashkent state transport university, Tashkent, Uzbekistan

**Abstract:** The railway is the busiest transport and properly designed and used will further improve efficiency. For this reason, this article gives the most convenient transition model in the section of rail lifting from one plane to another. That is, in order for the movement of the train in the ascent section to be smooth, the trajectory in the turn section must be an arc of a circle. The plane in which the train stands should be an attempt at this circle. It is optimal that the upper plane is also in the wobbling position along the circular arc on the lifting part.

**Keywords:** railway plan, rail track, steepness, radius of contact, angle of rotation, profile of carriage movement.

### 1. Introduction

Drawing up a railway plan depends on the terrain conditions, consists of rectilinear parts and curved parts connecting rectilinear parts [1], [2]. A simple version of a curved part is a scheme where both straight parts belong on the same horizontal plane. We consider it difficult when the straight part is laid on horizontal planes at different levels. This variant also splits into two

- angle between straight parts is equal to zero,
- angle between straight parts

In this article, we will draw a curve equation describing the location of the railway and road plan path.

### 2. Content

The longitudinal profile of a railway line is the projection of its axis onto a vertical surface, which is then turned onto the plane [3], [4].

The ideal longitudinal profile is a straight line on a horizontal plane. But the geological and topographic features of the area through which the railway is traced cause the direction of the road to change or move to another level of the horizontal plane. These changes may occur simultaneously or will be repeated several times. In this case, the railway plan is considered complicated.

One simpler view of the difficult part of the road is to raise the level of the railway to some height  $\delta$ , while the direction of the road does not change. This is indicated in Figure 1.

Here  $\alpha$  and  $\beta$  are different horizontal planes, the distance between them is  $\delta$ . The projection of the straight part  $b$  onto the horizontal plane  $\alpha$  is denoted by  $b'$  and it belongs to  $\alpha$ , the straight line  $b'$  is a continuation of the straight line  $a$ .

For lifting  $\delta$  railway, there are strict conditions that provide the technical possibility of moving the train along this road [5-7]. The rise of road  $\delta$  is associated with the overcoming by the railway of various kinds of high-altitude obstacles in the vertical plane. Depending on the direction, movement  $\delta$  may indicate go or descent.

Usually on the railway, the rise or descent is called the steepness of the road [8], [9].

Sections of a profile of unambiguous slope are called a longitudinal profile element. In this diagram, segment  $AB$  is a longitudinal profile element.

Slope steepness  $AB$  is considered to be the main characteristics of the longitudinal profile.

Slope steepness is measured by the ratio of lifting (lowering) height  $\delta$  in meters as a horizontal projection of its length  $l$  – in kilometers [10].

The length of the profile element is usually measured not by the hypotenuse  $AB$  of the triangle  $ABC$ , but by the leg  $AC$ , that is, by the projection  $AB$  on the horizontal plane  $\alpha$ .

We are interested in the optimal mathematical model of the longitudinal profile. Therefore, parameters  $\delta$  and  $AC = l$  are considered to meet all technical and economic requirements.

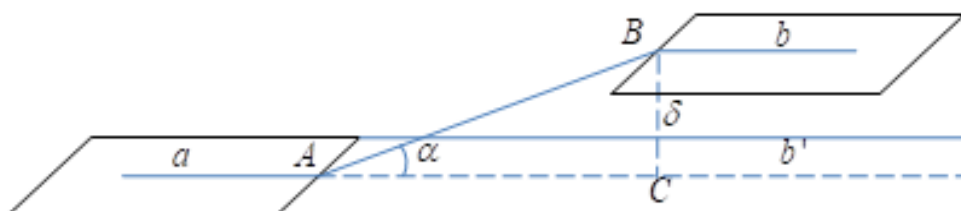
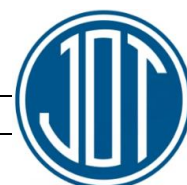


Fig. 1. Raising the level of the railway to height  $\delta$ .

<sup>a</sup>  <https://orcid.org/0000-0001-6228-8749>

<sup>b</sup>  <https://orcid.org/0009-0006-2781-9325>



We offer the most optimal version of the longitudinal profile, which ensures the most continuous movement of the composition without changing the speed of movement.

To do this, enter the Cartesian coordinate system, the abscissa coinciding with line  $a$ , select the origin  $O$  in the middle of segment  $AC$ , then  $AO = OC$ . The direction of the  $Oy$  axis perpendicular to the horizontal  $\alpha$  plane. Then the considered points have the following coordinates  $A(-\frac{l}{2}, 0)$ ,  $C(\frac{l}{2}, 0)$ . The intersection of  $AB$  with the axis has coordinates  $D(0, \frac{\delta}{2})$ . Equation of the line  $b$ :  $y = \delta$ .

Select the curve connecting points  $A$  and  $D$  ( $D$  and  $C$ ) so that it is defined by one arc of the circle. Moreover, at point  $A$ , line  $a$  should be tangent to this circle. This means that its center must lie on line  $x = -\frac{l}{2}$ . We will put a similar requirement for arc  $DC$ . At points  $B$ , line  $b$  will be tangent to the circle connecting points  $D$  and  $B$ . At point  $D$ , these two circles must have a single tangent. Then we have at point  $D$  a smooth transition from arc  $AD$  to arc  $DC$ . Note that the center of the circle expressing arc  $DC$  belongs to line  $x = \frac{l}{2}$  and is located symmetrically to the center of the circle of arc  $AD$  relative to point  $D$ .

Define the center of a circle  $E$  having an arc  $AD$  satisfying the above conditions. Segment  $AD$  is the chord of this circle. Therefore, the centre  $E_1$  must lie on a straight line  $T_1$  which is perpendicular to the length  $AD$  and which runs in its middle.

Let's calculate the equation of the line  $AD$  as a line passing through points  $A(-\frac{l}{2}, 0)$  and  $D(0, \frac{\delta}{2})$ .

$$AD: y = \frac{\delta}{l}x + \frac{\delta}{2}, \quad R = \frac{\delta}{l}$$

The middle of chord  $AD$  has coordinates  $(-\frac{l}{4}, \frac{\delta}{4})$ . The equation of line  $T_1$  perpendicular to the line is defined as a line passing through point  $(-\frac{l}{4}, \frac{\delta}{4})$  and perpendicular to line  $AD$ . From the condition of perpendicularity, the angular coefficient of the line  $T_1$  is determined from equality  $R = -\frac{1}{R_1} = -\frac{l}{\delta}$ .

Then equation  $T_1$  has the form

$$y = \frac{\delta}{l}x + \delta$$

Define the coordinates of the center  $E_1$  as the intersection of the lines

$$\begin{cases} x = -\frac{l}{2}, \\ y = \frac{\delta}{l}x + \delta. \end{cases}$$

Then  $E_1$  has coordinates  $(-\frac{l}{2}, \frac{3l^2 + \delta^2}{4\delta})$

The radius of circle  $R_1$  is equal to the distance between point  $E_1$  and axis  $Ox$ , therefore

$$R_1 = \frac{l^2 + \delta^2}{4\delta}$$

The equation of the circle to the center at point  $E$  and radius  $R$  is

$$\left(y - \frac{l^2 + \delta^2}{4\delta}\right)^2 + \left(x + \frac{l}{2}\right)^2 = \left(\frac{l^2 + \delta^2}{4\delta}\right)^2$$

From this one can obtain the equation of arc  $AD$

$$y = \sqrt{\left(\frac{l^2 + \delta^2}{4\delta}\right)^2 - \left(x + \frac{l}{2}\right)^2} \quad (1)$$

This equation makes it possible to determine the coordinate of arc  $AD$  with sufficient accuracy, given the values of parameters  $l$  and  $\delta$ .

In a similar way, you can define a circle equation in which  $DB$  is an arc.

The equation of arc  $DB$  is

$$y = \sqrt{\left(\frac{l^2 + \delta^2}{4\delta}\right)^2 - \left(x - \frac{l}{2}\right)^2} \quad (2)$$

It is easy to prove that the arcs defined by equation (1) and (2) intersect at point  $D(0, \frac{\delta}{2})$  and at this point both curves have a single tangent.

The arcs defined by equations (1) and (2) may be referred to as the transition portions of the longitudinal profile of the railway line. Then point  $D$  is an inflection point. Besides, arc  $AD$  will be concave, and arc  $DB$  will be convex part of transition part. In this case, the transition part of the longitudinal profile is considered half of the entire rise.

When the lift  $AB$  is protracted, i.e. the length  $l$  is sufficiently large and the steepness determined by the value  $\delta$  is relatively large, the inflection point  $D$  can be replaced by segments  $D_1D_2$  so that the straight line  $D_1D_2$  is tangent to both parts of the transition part defined by equation (1) and (2).

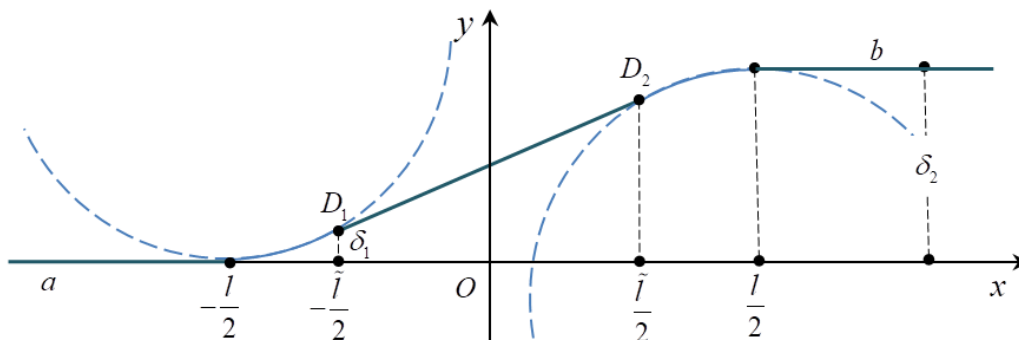


Fig. 2. Connection type with sufficiently large gap between lifts

In this case,  $\delta_1$  and  $\delta_2$  are determined by the choice of interval  $\left(-\frac{l}{2}, \frac{l}{2}\right)$  and the condition of parallelism to chord  $AD$ .

### 3. Conclusion

When the ends of the rectilinear part of the railway track plan belong to different horizontal planes, the distance between which is  $\delta$ , the steepness of the road appears [11-13]. To ensure a smooth transition from a horizontal straight line to a straight line with a given steepness, the arcs of the circles defined by equation (1) and (2) can be taken as the transition part of the longitudinal profile of the railway line. When the lifting part of the road is protracted, that is,  $l$  is large enough, the inflection point can be replaced with a straight segment determined with the specifications.

### References

- [1] Verbilo V.A., Kozhedub S.S. Fundamentals of designing single-track railways: educational method. Allowance; M-transp. and communications Rep. Belarus, Belorussian. state University of Transport – Gomel: BelGUT, 2018. – 139 p.
- [2] Dyunin A.K, Protsenko A.I. Analytical method for designing the reconstruction of railway tracks in plan. Novosibirsk Publishing house NIIZhT – 1967 226s.
- [3] Golovanov N.N. Geometric modeling. M. Publishing House of Physics and Mathematical Literature – 2002. 476 p.
- [4] Korzhenevich I.P. Mathematical model of the layout of an existing railway track. Science and process of transport. Herald. Dnepropetrovsk National University of Railway Transport. Mathematics. 2007.
- [5] Gavash T., Jilcha K. Design risk modeling and analysis for railway construction projects. / International journal of construction management. Volume 23. Issue 14. – 2023. 2488-2498.
- [6] Norberg A. Implementing building information modeling within the railway sector. / A. Norberg. Goteborg, Sweden: 2012.
- [7] Krivchenya I.N., Dubrovskaya T.A. Application of mathematical modeling methods in the design of railway reconstruction. Journal Famous Transsib. Construction and architecture. 2019.
- [8] Levchenkova E.P. Development of mathematical models of the railway route for plan reconstruction. Dissertation of a candidate of sciences in the Russian Federation.05.02.06. 2019.
- [9] Ponarin A.S. Mathematical models in railway routing. Moscow. 1995.
- [10] Dynnikov I.A. Classical differential geometry. Lecture course. Moscow State University, Moscow, 2019.
- [11] Mamitko A.A. Automatic construction of the railway line plan structure//Transport infrastructure of the Siberian region: materials IV all-Russia. scientific-practical. conf. with international. participation: in 2 t. Irkutsk, 2013. S. 516-521.
- [12] Treskinsky S.A., Khudyakova I.G. Physical basis of clothoid tracing. M: Magazine "Highways", No. 5, 1963
- [13] Kravchenko O.A. Biclotoid design of curved sections of railways. Dissertations for the degree of candidate of technical sciences. Moscow-2012

### Mualliflar bo'yicha ma'lumot/ Information about the authors

Artybaev Abdullaaziz	Tashkent state transport university. Professor of the department of Higher Mathematics. E-mail: aartykbaev@mail.ru Tel.:+99891 136 13 31 <a href="https://orcid.org/0000-0001-6228-8749">https://orcid.org/0000-0001-6228-8749</a>
Toshmatova Mokhiniso Murodulla kizi	Tashkent state transport university. Basic doctoral student of the department of Higher Mathematics. E-mail: toshmatova_mm@mail.ru Tel.:+99890 007 50 10 <a href="https://orcid.org/0009-0006-2781-9325">https://orcid.org/0009-0006-2781-9325</a>

